

Partie I

1). Comme  $[\hat{p}_x, \hat{p}_y] = 0$ , on a

$$[\hat{p}_x^2, \hat{p}_y^2] = \hat{p}_x^2 \hat{p}_y^2 - \hat{p}_y^2 \hat{p}_x^2 = 0$$

De même,  $[\hat{p}_x^2, \hat{y}^2] = [\hat{p}_y^2, \hat{x}^2] = [\hat{x}^2, \hat{y}^2] = 0$ . Alors

$$[\hat{H}_x, \hat{H}_y] = [\hat{p}_x^2 + \hat{x}^2, \hat{p}_y^2 + \hat{y}^2] = [\hat{p}_x^2, \hat{p}_y^2] + [\hat{p}_x^2, \hat{y}^2] + [\hat{x}^2, \hat{p}_y^2] + [\hat{x}^2, \hat{y}^2] = 0$$

2). Par exemple,

$$[\hat{H}, \hat{H}_x] = [\hat{H}_x + \hat{H}_y, \hat{H}_x] = \underbrace{[\hat{H}_x, \hat{H}_x]}_0 + \underbrace{[\hat{H}_y, \hat{H}_x]}_0 = 0 \quad \text{d'après 1).}$$

$$3). [\hat{H}, \hat{L}_z] = [\hat{p}_x^2 + \hat{x}^2 + \hat{p}_y^2 + \hat{y}^2, \hat{L}_z] = [\hat{H}_x + \hat{H}_y, \hat{L}_z] = [\hat{H}_x, \hat{L}_z] + [\hat{H}_y, \hat{L}_z] =$$

Où = par conséquent

$$[\hat{H}_x, \hat{L}_z] = [\hat{p}_x^2 + \hat{x}^2, \hat{x}\hat{p}_y - \hat{y}\hat{p}_x] =$$

$$= [\hat{p}_x^2, \hat{x}\hat{p}_y] - [\hat{p}_x^2, \hat{y}\hat{p}_x] + [\hat{x}^2, \hat{x}\hat{p}_y] - [\hat{x}^2, \hat{y}\hat{p}_x]$$

$\underbrace{\quad}_0 \quad \underbrace{\quad}_0 \quad \text{car } [\hat{x}, \hat{x}] = 0$   
 $\text{car } [\hat{p}_x, \hat{p}_x] = [\hat{p}_x, \hat{y}] = 0 \quad = [\hat{x}, \hat{p}_x] = 0$

$$= [\hat{p}_x^2, \hat{x}\hat{p}_y] - [\hat{x}^2, \hat{y}\hat{p}_x] =$$

$$= [\hat{p}_x^2, \hat{x}] \hat{p}_y + \hat{x} [\hat{p}_x^2, \hat{p}_y] - [\hat{x}^2, \hat{y}] \hat{p}_x - \hat{y} [\hat{x}^2, \hat{p}_x]$$

$\underbrace{\quad}_0 \quad \underbrace{\quad}_0$

$$= [\hat{p}_x^2, \hat{x}] \hat{p}_y - \hat{y} [\hat{x}^2, \hat{p}_x] =$$

$$= \hat{p}_x [\hat{p}_x, \hat{x}] \hat{p}_y + [\hat{p}_x, \hat{x}] \hat{p}_x \hat{p}_y - \hat{y} [\hat{x}, \hat{p}_x] \hat{x} - \hat{y} \hat{x} [\hat{x}, \hat{p}_x]$$

$\underbrace{\quad}_{-i} \quad \underbrace{\quad}_{-i} \quad \underbrace{\quad}_0 \quad \underbrace{\quad}_{-i}$

$$= -i \hat{p}_x \hat{p}_y - i \hat{p}_x \hat{p}_y - i \hat{y} \hat{x} - i \hat{y} \hat{x} = -2i (\hat{x} \hat{y} + \hat{p}_x \hat{p}_y)$$

(notons que  $\hat{x} \hat{y} = \hat{y} \hat{x}$  et  $\hat{p}_x \hat{p}_y = \hat{p}_y \hat{p}_x$ )

De la même manière,

$$\begin{aligned}
 [\hat{H}_y, \hat{L}_z] &= [\hat{p}_y^2 + \hat{y}^2, \hat{x}\hat{p}_y - \hat{y}\hat{p}_x] = \\
 &= \underbrace{[\hat{p}_y^2, \hat{x}\hat{p}_y]}_0 - [\hat{p}_y^2, \hat{y}\hat{p}_x] + \underbrace{[\hat{y}^2, \hat{x}\hat{p}_y]}_0 - \underbrace{[\hat{y}^2, \hat{y}\hat{p}_x]}_0 = \\
 &= -[\hat{p}_y^2, \hat{y}\hat{p}_x] + [\hat{y}^2, \hat{x}\hat{p}_y] = \\
 &= -[\hat{p}_y^2, \hat{y}]\hat{p}_x - \hat{y}[\hat{p}_y^2, \hat{p}_x] + \underbrace{[\hat{y}^2, \hat{x}]\hat{p}_y}_0 + \hat{x}\underbrace{[\hat{y}^2, \hat{p}_y]}_0 = \\
 &= -[\hat{p}_y^2, \hat{y}]\hat{p}_x + \hat{x}[\hat{y}^2, \hat{p}_y] = \\
 &= -\underbrace{[\hat{p}_y, \hat{y}]\hat{p}_y}_{\vdots} \hat{p}_x - \hat{p}_y \underbrace{[\hat{p}_y, \hat{y}]\hat{p}_x}_{\vdots} + \hat{x}\hat{y}\underbrace{[\hat{y}, \hat{p}_y]}_{\vdots} + \hat{x}\underbrace{[\hat{y}, \hat{p}_y]\hat{y}}_{\vdots} = \\
 &= 2i\hat{p}_x\hat{p}_y + 2i\hat{x}\hat{y}.
 \end{aligned}$$

Donc  $[\hat{H}, \hat{L}_z] = [\hat{H}_x, \hat{L}_z] + [\hat{H}_y, \hat{L}_z] = -2i(\hat{x}\hat{y} + \hat{p}_x\hat{p}_y) + 2i(\hat{x}\hat{y} + \hat{p}_x\hat{p}_y) = 0$

a). On vient de montrer que

$$[\hat{H}_y, \hat{L}_z] = 2i(\hat{x}\hat{y} + \hat{p}_x\hat{p}_y) \implies \hat{K} = \hat{x}\hat{y} + \hat{p}_x\hat{p}_y$$

b).  $2i[\hat{H}, \hat{K}] = [\hat{H}, 2i\hat{K}] = [\hat{H}, [\hat{H}_y, \hat{L}_z]] =$

$$= [\hat{H}, \hat{H}_y\hat{L}_z - \hat{L}_z\hat{H}_y] =$$

$$= \hat{H}(\hat{H}_y\hat{L}_z - \hat{L}_z\hat{H}_y) - (\hat{H}_y\hat{L}_z - \hat{L}_z\hat{H}_y)\hat{H} = 0$$

(car  $\hat{H}$  commute avec  $\hat{H}_y$  et  $\hat{L}_z$ ).

c).  $[\hat{H}_x, \hat{K}] = [\hat{p}_x^2 + \hat{x}^2, \hat{x}\hat{y} + \hat{p}_x\hat{p}_y] =$

$$= [\hat{p}_x^2, \hat{x}\hat{y}] + \underbrace{[\hat{p}_x^2, \hat{p}_x\hat{p}_y]}_0 + \underbrace{[\hat{x}^2, \hat{x}\hat{y}]}_0 + [\hat{x}^2, \hat{p}_x\hat{p}_y]$$

$$= [\hat{p}_x^2, \hat{x}\hat{y}] + [\hat{x}^2, \hat{p}_x\hat{p}_y] =$$

$$= \underbrace{[\hat{p}_x^2, \hat{x}]\hat{y}}_0 + \hat{x}\underbrace{[\hat{p}_x^2, \hat{p}_x]}_0 + \underbrace{[\hat{x}^2, \hat{p}_x]\hat{p}_y}_0 + \hat{p}_x\underbrace{[\hat{x}^2, \hat{p}_y]}_0$$

$$= [\hat{p}_x^2, \hat{x}] \hat{y} + [\hat{x}^2, \hat{p}_x] \hat{p}_y =$$

$$= \underbrace{\hat{p}_x [\hat{p}_x, \hat{x}] \hat{y}}_{\vdots} + \underbrace{[\hat{p}_x, \hat{x}] \hat{p}_x \hat{y}}_{\vdots} + \underbrace{[\hat{x}, \hat{p}_x] \hat{x} \hat{p}_y}_{\vdots} + \hat{x} \underbrace{[\hat{x}, \hat{p}_x] \hat{p}_y}_{\vdots} =$$

$$= -2i \hat{p}_x \hat{y} + 2i \hat{x} \hat{p}_y = 2i (\hat{x} \hat{p}_y - \hat{y} \hat{p}_x) = 2i \hat{L}_z$$

$$(car \hat{p}_x \hat{y} = \hat{y} \hat{p}_x)$$

Donc  $[\hat{H}_x, \hat{K}] = 2i \hat{L}_z$ . De plus

$$[\hat{H}_y, \hat{K}] = [\hat{H} - \hat{H}_x, \hat{K}] = \underbrace{[\hat{H}, \hat{K}]}_{=0} - [\hat{H}_x, \hat{K}] =$$

d'après SI.

$$= -[\hat{H}_x, \hat{K}] = -2i \hat{L}_z.$$

Finalement:

$$[\hat{L}_z, \hat{K}] = [\hat{x} \hat{p}_y - \hat{y} \hat{p}_x, \hat{x} \hat{y} + \hat{p}_x \hat{p}_y] =$$

$$= [\hat{x} \hat{p}_y, \hat{x} \hat{y}] + [\hat{x} \hat{p}_y, \hat{p}_x \hat{p}_y] - [\hat{y} \hat{p}_x, \hat{x} \hat{y}] - [\hat{y} \hat{p}_x, \hat{p}_x \hat{p}_y] =$$

$$= \hat{x} [\hat{p}_y, \hat{x} \hat{y}] + \underbrace{[\hat{x}, \hat{x} \hat{y}]}_0 \hat{p}_y + \hat{x} \underbrace{[\hat{p}_y, \hat{p}_x \hat{p}_y]}_0 + [\hat{x}, \hat{p}_x \hat{p}_y] \hat{p}_y$$

$$- \hat{y} [\hat{p}_x, \hat{x} \hat{y}] - \underbrace{[\hat{y}, \hat{x} \hat{y}]}_0 \hat{p}_x - \hat{y} \underbrace{[\hat{p}_x, \hat{p}_x \hat{p}_y]}_0 - [\hat{y}, \hat{p}_x \hat{p}_y] \hat{p}_x =$$

$$= \hat{x} [\hat{p}_y, \hat{x} \hat{y}] + [\hat{x}, \hat{p}_x \hat{p}_y] \hat{p}_y - \hat{y} [\hat{p}_x, \hat{x} \hat{y}] - [\hat{y}, \hat{p}_x \hat{p}_y] \hat{p}_x =$$

$$= \hat{x} \underbrace{[\hat{p}_y, \hat{x}]}_0 \hat{y} + \hat{x}^2 \underbrace{[\hat{p}_y, \hat{y}]}_{\vdots} + \underbrace{[\hat{x}, \hat{p}_x]}_{\vdots} \hat{p}_y^2 + \hat{p}_x \underbrace{[\hat{x}, \hat{p}_y]}_0 \hat{p}_y$$

$$- \hat{y} \underbrace{[\hat{p}_x, \hat{x}]}_{\vdots} \hat{y} - \hat{y} \hat{x} \underbrace{[\hat{p}_x, \hat{y}]}_0 - \underbrace{[\hat{y}, \hat{p}_x]}_0 \hat{p}_y \hat{p}_x - \hat{p}_x \underbrace{[\hat{y}, \hat{p}_y]}_{\vdots} \hat{p}_x =$$

$$= -i \hat{x}^2 + i \hat{p}_y^2 + i \hat{y}^2 - i \hat{p}_x^2 = -i(\hat{p}_x^2 + \hat{x}^2) + i(\hat{p}_y^2 + \hat{y}^2) =$$

$$= i(\hat{H}_y - \hat{H}_x).$$

7). Le spectre de  $\hat{H}$  est dégénéré:

- prenons par exemple un vecteur propre commun  $f$  de  $\hat{H}$  et  $\hat{L}_z$ , avec les valeurs propres correspondantes  $E$  et  $m$ , c'est-à-dire,

$$\hat{H} f = E f, \quad \hat{L}_z f = m f.$$

- Considérons le vecteur  $g = \hat{H}_x f$ . Nous avons

$$\hat{H} g = \hat{H} \hat{H}_x f = \hat{H}_x \hat{H} f = \hat{H}_x E f = E \hat{H}_x f = E g$$

$$\begin{aligned} \hat{L}_z g &= \hat{L}_z \hat{H}_x f = [\hat{L}_z, \hat{H}_x] f + \hat{H}_x \hat{L}_z f = \\ &= 2i \hat{K} f + \hat{H}_x m f = \\ &= 2i \hat{K} f + m g \end{aligned}$$

Donc  $g$  est un nouveau vecteur propre de  $\hat{H}$  avec la même énergie (nouveau car en général  $\hat{K} f \neq 0$  et donc il est impossible d'avoir  $g \sim f$ , sinon  $\hat{L}_z g = m g$ ).

## Partie II

$$\left( -\frac{d^2}{dx^2} + x^2 + gx^3 - E \right) \psi = 0$$

1. Tout d'abord on constate que l'ansatz naïf

$$\psi(x) \sim a x^D + o(x^D)$$

ne marche pas, car dans ce cas

$$-a D(D-1) x^{D-2} + o(x^{D-2}) + a x^{D+2} + o(x^{D+2})$$

$$+ g a x^{D+3} + o(x^{D+3}) - E a x^D + o(x^D) = 0$$

$$g a + o(1) = 0 \Rightarrow a = 0.$$

2. On essaie donc

$$\psi(x) \sim x^D e^{P(x)} (1 + o(1)) \quad \text{avec } P(x) = A x^d + \dots$$

En introduisant  $g = \ln y \Leftrightarrow y = e^g$  on a

$$y' = e^g g'$$

$$y'' = e^g (g'' + (g')^2)$$

$$g(x) = Ax^{-d} + o(x^{-d})$$

et alors :

$$-g'' - (g')^2 + x^2 + gx^3 - E = 0$$

$$-A^2 d(d-1)x^{d-2} + o(x^{d-2}) - A^2 d^2 x^{2d-2} + o(x^{2d-2}) + x^2 + gx^3 - E = 0$$

Nous avons 2 candidats pour le terme dominant :

- $A^2 d^2 x^{2d-2} \Rightarrow A=0 \Rightarrow$  contradiction
- $gx^3 \Rightarrow g=0 \Rightarrow$  contradiction

Donc ces 2 termes doivent se compenser :

$$gx^3 = A^2 d^2 x^{2d-2}$$

$\Downarrow$

$$\begin{cases} g = A^2 d^2 & \Rightarrow A = \pm \left(\frac{4}{25} g\right)^{1/2} = \pm \frac{2}{5} \sqrt{g} \\ 2d-2=3 & \Rightarrow d = 5/2 \end{cases}$$

Comme la puissance qui apparaît est  demi-entière , il n'est pas clair a priori quelle sera la forme des termes suivants dans le développement de  $f(x)$ .

Au lieu d'essayer les trouver "expérimentalement", passons par changement de variables

$$x = y^2 \Rightarrow$$

$$\frac{df}{dx} = \frac{1}{2y} \frac{df}{dy}$$

$$\frac{d^2 f}{dx^2} = \frac{1}{2y} \frac{d}{dy} \left( \frac{1}{2y} \frac{df}{dy} \right) = \frac{1}{4y^2} \frac{d^2 f}{dy^2} - \frac{1}{4y^3} \frac{df}{dy}$$

L'équation pour  $g$  devient

$$-\frac{1}{4y^2} \frac{d^2 g}{dy^2} + \frac{1}{4y^3} \frac{dg}{dy} - \frac{1}{4y^2} \left( \frac{dg}{dy} \right)^2 + y^4 + gy^6 - E = 0$$

$$-\frac{d^2 f}{dy^2} + \frac{1}{y} \frac{df}{dy} - \left(\frac{df}{dy}\right)^2 + 4y^6 + 4gy^8 - 4Ey^2 = 0$$

On cherche la solution sous la forme

$$f(y \rightarrow \infty) \sim Ay^d + o(y^d)$$

$$-A d(d-1)y^{d-2} + o(y^{d-2}) + A d y^{d-2} + o(y^{d-2})$$

$$-A^2 d^2 y^{2d-2} + o(y^{2d-2}) + 4y^6 + 4gy^8 - 4Ey^2 = 0$$

Le raisonnement analogue au précédent conduit à

$$\begin{cases} A^2 d^2 = 4g \Rightarrow A = \pm \frac{2}{\sqrt{g}} \sqrt{g} \\ 2d-2 = 8 \Rightarrow d=5 \end{cases}$$

Le développement plus détaillé est donc de la forme

$$f(y \rightarrow \infty) \sim \pm \frac{2}{\sqrt{g}} \sqrt{g} y^5 + \alpha y^4 + \beta y^3 + \gamma y^2 + \delta y + \epsilon \ln y$$

Donc :

$$-\left[ \pm \frac{2}{\sqrt{g}} \sqrt{g} \cdot 8 \cdot 4 \cdot y^3 + \alpha \cdot 4 \cdot 3 \cdot y^2 + \beta \cdot 3 \cdot 2 \cdot y + \gamma \cdot 2 \cdot 1 - \frac{\nu}{y^2} + o\left(\frac{1}{y^2}\right) \right]$$

$-\frac{d^2 f}{dy^2}$

$$+ \frac{1}{y} \left[ \pm \frac{2}{\sqrt{g}} \sqrt{g} \cdot 8 \cdot y^4 + \alpha \cdot 4 \cdot y^3 + \beta \cdot 3 \cdot y^2 + \gamma \cdot 2 \cdot y + \delta + \frac{\nu}{y} + o\left(\frac{1}{y}\right) \right]$$

$\frac{1}{y} \frac{df}{dy}$

$$-\left[ \pm \frac{2}{\sqrt{g}} \sqrt{g} \cdot 8 y^4 + \alpha \cdot 4 y^3 + \beta \cdot 3 y^2 + \gamma \cdot 2 y + \delta + \frac{\nu}{y} + o\left(\frac{1}{y}\right) \right]^2 +$$

$\left(\frac{df}{dy}\right)^2$

$$+ 4y^6 + 4gy^8 - 4Ey^2 = 0$$

Le terme inconnu le plus grand correspond au produit

$$\pm \frac{2}{\sqrt{g}} \sqrt{g} \cdot 8 y^4 \cdot o\left(\frac{1}{y}\right), \quad (\sim o(y^3))$$

donc on gardera les termes jusqu'à  $y^3$  dans les développements.

$$+ \frac{2}{\sqrt{g}} \sqrt{g} \cdot 8 \cdot 4 \cdot y^3 + \frac{2}{\sqrt{g}} \sqrt{g} \cdot 8 y^3$$

$$- 4g y^8 - 16g^2 y^6 - 9\beta^2 y^4$$

$$+ 2 \cdot 2\sqrt{g} \cdot 4\alpha y^4 + 2 \cdot 2\sqrt{g} \cdot 3\beta y^6 + 2 \cdot 2\sqrt{g} \cdot 2\delta y^8$$

$$+ 2 \cdot 2\sqrt{g} \cdot 8 y^4 + 2 \cdot 2\sqrt{g} \cdot 2 y^3$$

$$- 2 \cdot 4\alpha \cdot 3\beta \cdot y^5 - 2 \cdot 4\alpha \cdot 2\delta y^4 - 2 \cdot 4\alpha \cdot 8 y^3$$

$$- 2 \cdot 3\beta \cdot 2\delta \cdot y^3 + 4y^6 + 4g y^8 - 4y^2 + o(y^3) = 0$$

On voit que  $\alpha = 0$  (coef. de  $y^4$ )

Donc

$$+ 6\sqrt{g} y^3 - 9\beta^2 y^4 + 2 \cdot 2\sqrt{g} \cdot 3\beta \cdot y^6 + 2 \cdot 2\sqrt{g} \cdot 2\delta y^8$$

$$+ 2 \cdot 2\sqrt{g} \cdot 8 y^4 + 2 \cdot 2\sqrt{g} \cdot 2 y^3 - 2 \cdot 3\beta \cdot 2\delta \cdot y^3$$

$$+ 4y^6 + o(y^3) = 0$$

Par la suite  $\delta = 0$  (grâce au coef. de  $y^8$ ), alors

$$(4 + 12\sqrt{g}\beta) y^6 + (-9\beta^2 + 4\sqrt{g}8) y^4$$

$$+ (6\sqrt{g} + 4\sqrt{g}2) y^3 + o(y^3) = 0.$$

Finalement :

$$\beta = \pm \frac{1}{2\sqrt{g}} \quad (\text{coef. de } y^6)$$

$$\delta = \pm \frac{9}{4\sqrt{g}} = \pm \frac{1}{4g\sqrt{g}} \quad (\text{coef. de } y^4)$$

$$\alpha = -\frac{\beta}{2} \quad (\text{coef. de } y^3)$$

$$y(y \rightarrow \infty) \sim \pm \left[ \frac{2}{\sqrt{g}} \sqrt{g} y^5 + \frac{1}{2\sqrt{g}} y^3 - \frac{1}{4g\sqrt{g}} y \right] - \frac{\beta}{2} e_n y$$

(

$$y(y \rightarrow \infty) = y^{-3/2} e^{\pm \left[ \frac{2}{\sqrt{g}} \sqrt{g} y^5 + \frac{1}{2\sqrt{g}} y^3 - \frac{1}{4g\sqrt{g}} y \right]} (1 + o(1))$$

En termes de  $x$ :

$$\psi(x \rightarrow \pm\infty) = |x|^{-3/4} e^{\pm \left[ \frac{2}{5} \sqrt{g} |x|^{5/2} + \frac{1}{3\sqrt{g}} |x|^{3/2} - \frac{1}{4g\sqrt{g}} |x|^{1/2} \right]} (1 + o(1)).$$

### Partie III

Les valeurs propres de  $\hat{L}^2$  sont de la forme  $l(l+1)$ , où  $l$  note le nombre quantique orbital.

$$l(l+1) = 6 \Rightarrow l^2 + l - 6 = 0$$

$$l_1 = 2, \quad l_2 = -3$$

↑  
cette solution est exclue car  $l = 0, 1, 2, \dots (\geq 0)$

Donc

1). les valeurs propres possibles de  $L_z$  sont  $-2, -1, 0, 1, 2$  (c'est-à-dire,  $-l, -l+1, \dots, l$ ).

2). les fonctions propres communes ortho-normalisées sont  $Y_2^{-2}(\theta, \varphi), Y_2^{-1}(\theta, \varphi), Y_2^0(\theta, \varphi), Y_2^1(\theta, \varphi), Y_2^2(\theta, \varphi)$

Explicitement :

$$Y_l^m(\theta, \varphi) = C_l^m P_l^m(\cos \theta) e^{im\varphi}$$

Notons que  $C_l^m = \sqrt{\frac{2^{l+1}}{4\pi} \frac{(l-m)!}{(l+m)!}}$  et donc

$$C_2^2 = \sqrt{\frac{5}{4\pi} \cdot \frac{(2-2)!}{(2+2)!}} = \sqrt{\frac{5}{96\pi}}$$

$$C_2^1 = \sqrt{\frac{5}{4\pi} \frac{(2-1)!}{(2+1)!}} = \sqrt{\frac{5}{24\pi}}$$

$$C_2^0 = \sqrt{\frac{5}{4\pi}}$$

De plus

$$P_l^m(\cos \theta) = \frac{(\sin \theta)^m}{2^l l!} \left[ \frac{d^{l+m}}{dz^{l+m}} (z^2 - 1)^l \right]_{z = \cos \theta} =$$

$$= (-1)^m \frac{(l+m)!}{(l-m)!} P_l^{-m}(z) \Big|_{z = \cos \theta} =$$

$$= (-1)^m \frac{(l+m)!}{(l-m)!} \cdot \frac{(\sin \theta)^{-m}}{2^l l!} \left[ \frac{d^{l-m}}{dz^{l-m}} (z^2 - 1)^l \right]_{z = \cos \theta}$$



et donc

$$P_2^2(\cos \theta) = \frac{(2+2)!}{(2-2)!} \cdot \frac{(\sin \theta)^{-2}}{2^2 \cdot 2!} \left[ \frac{d^0}{dz^0} (z^2-1)^2 \right]_{z=\cos \theta} =$$
$$= \frac{4!}{4 \cdot 2} \cdot \frac{1}{\sin^2 \theta} \underbrace{(\cos^2 \theta - 1)^2}_{-\sin^2 \theta} = 3 \sin^2 \theta$$

$$P_2^1(\cos \theta) = (-1) \frac{(2+1)!}{(2-1)!} \cdot \frac{(\sin \theta)^{-1}}{2^2 \cdot 2!} \left[ \frac{d^{2-1}}{dz^{2-1}} (z^2-1)^2 \right]_{z=\cos \theta} =$$
$$= -\frac{3}{2} \cdot \frac{1}{\sin \theta} \cdot \left[ \frac{d}{dz} (z^2-1)^2 \right]_{z=\cos \theta} =$$
$$= -\frac{3}{4} \cdot \frac{1}{\sin \theta} \cdot [2(z^2-1) \cdot 2z]_{z=\cos \theta} =$$
$$= -\frac{3}{4} \cdot \frac{1}{\sin \theta} \cdot 4 \cos \theta \underbrace{(\cos^2 \theta - 1)}_{-\sin^2 \theta} = 3 \sin \theta \cos \theta$$

$$P_2^0(\cos \theta) = \frac{1}{2^2 \cdot 2!} \left[ \frac{d^2}{dz^2} (z^2-1)^2 \right]_{z=\cos \theta} =$$
$$= \frac{1}{8} \left[ \frac{d^2}{dz^2} (z^4 - 2z^2 + 1) \right]_{z=\cos \theta} =$$
$$= \frac{1}{8} (12z^2 - 4)_{z=\cos \theta} = \frac{3 \cos^2 \theta - 1}{2}$$

Par conséquent, nous avons

$$Y_2^2(\theta, \varphi) = \sqrt{\frac{5}{96\pi}} \cdot 3 \sin^2 \theta e^{2i\varphi} = \sqrt{\frac{15}{32\pi}} \sin^2 \theta e^{2i\varphi}$$

$$Y_2^1(\theta, \varphi) = \sqrt{\frac{5}{24\pi}} \cdot 3 \sin \theta \cos \theta e^{i\varphi} = \sqrt{\frac{15}{8\pi}} \sin \theta \cos \theta e^{i\varphi}$$

$$Y_2^0(\theta, \varphi) = \sqrt{\frac{5}{4\pi}} \cdot \frac{3 \cos^2 \theta - 1}{2}$$

De plus, en utilisant  $Y_\ell^{-m}(\theta, \varphi) = (-1)^m \overline{Y_\ell^m(\theta, \varphi)}$ , on a

$$Y_2^{-2}(\theta, \varphi) = \overline{Y_2^2(\theta, \varphi)} = \sqrt{\frac{15}{32\pi}} \sin^2 \theta e^{-2i\varphi}$$

$$Y_2^{-1}(\theta, \varphi) = -\overline{Y_2^1(\theta, \varphi)} = -\sqrt{\frac{15}{8\pi}} \sin \theta \cos \theta e^{-i\varphi}$$